

LIE ALGEBRA OF ISOMETRIES OF A RIEMANNIAN MANIFOLD

Let (M, g) be Riem. manifold.

Def. A Killing v.f. is v.f. $\zeta \in \mathfrak{X}(M)$ s.t. $\mathcal{L}_\zeta g = 0$

Let $\zeta \in \mathfrak{X}(M)$ and define $A_\zeta: TM \rightarrow TM$ by

$$A_\zeta(Y) := -\nabla_Y \zeta$$

where ∇ is Levi-Civita connection.

LEMMA ζ is Killing iff A_ζ is section of $\mathfrak{so}(TM)$.

$$\begin{aligned} (g(A_\zeta Y, Z) &= -g(\nabla_Y \zeta, Z) = \\ &\downarrow \text{def.} \qquad \qquad \qquad \downarrow \nabla \text{ is torsion-free} \\ &= g([Z, Y], Z) - g(\nabla_Z Y, Z) \\ &= \zeta(g(Y, Z)) - g(Y, [Z, Z]) - g(\nabla_Z Y, Z) \\ &\downarrow \zeta \text{ is Killing} \\ &= g(Y, \nabla_Z Z) - g(Y, [Z, Z]) \\ &\downarrow \nabla \text{ is metric} \\ &= g(Y, \nabla_Z \zeta) = -g(Y, A_\zeta Z) \\ &\downarrow \nabla \text{ is torsion-free} \end{aligned}$$

We want to introduce Killing transport: how to think of Killing v.f. or parallel sections of some bundle.

Consider bundle.

$$E = TM \oplus S(TM)$$

and let us define covariant derivative D on E by

$$D_X(\zeta, A) := (\nabla_X \zeta + A(X), \nabla_X A - R(X, \zeta))$$

where $R_{XY} = \nabla_{[X, Y]} - \nabla_X \nabla_Y + \nabla_Y \nabla_X$ is curvature of ∇ .

PROPOSITION: Parallel sections of E w.r.t. D are precisely the Killing vectors. [KOPFMAN 1955, GEROCH 1969]

Pf.

$$D_X(\zeta, A) = 0 \text{ iff } \begin{cases} A(X) = -\nabla_X \zeta \\ \nabla_X A = R(X, \zeta) \end{cases} \quad \begin{array}{l} \text{(i.e. } A = A_\zeta \\ \text{and } \zeta \text{ is Killing)} \end{array}$$

We need to show that second identity is automatically satisfied. This is "Killing's identity".

$$\begin{aligned}
 (\nabla_X A) Y &= \nabla_X (AY) - A(\nabla_X Y) \\
 &= -\nabla_X \nabla_Y Z + \nabla_{\nabla_X Y} Z \\
 &\quad \downarrow \\
 &\quad A = A_Z
 \end{aligned}$$

→ we take difference

$$\begin{aligned}
 (\nabla_X A) Y - (\nabla_Y A) X &= -\nabla_X \nabla_Y Z + \nabla_{\nabla_X Y} Z \\
 &\quad + \nabla_Y \nabla_X Z - \nabla_{\nabla_Y X} Z \\
 &= -\nabla_X \nabla_Y Z + \nabla_Y \nabla_X Z + \nabla_{[X, Y]} Z \\
 &\quad \leftarrow \nabla \text{ is torsion-free} \\
 &= R(X, Y) Z
 \end{aligned}$$

We now use algebraic Bianchi Identity

$$R(X, Y)Z + R(Y, Z)X + R(Z, X)Y = 0$$

to arrive at

$$(\nabla_X A) Y - R(X, Z)Y = (\nabla_Y A) X - R(Y, Z)X$$

symmetric in $X \leftrightarrow Y$

On the other hand

$$\begin{aligned}
 g(\underbrace{(\nabla_X A) Y - R(X, Z)Y}_\in \Gamma(\mathfrak{so}(TM)}, \underbrace{Z}_\in \Gamma(\mathfrak{so}(TM)}) &= -g(\underbrace{(\nabla_X A) Z - R(X, Z)Z}_\in \Gamma(\mathfrak{so}(TM)}, \underbrace{Y}_\in \Gamma(\mathfrak{so}(TM)))
 \end{aligned}$$

whence $\nabla A - R(-, z) \in (\rho(T_x M) \otimes T_x^* M) \cap T_x M \otimes \mathcal{O}^2 T_x^* M$

at any $x \in M$. This space is easily seen to be zero. \blacksquare

$$\begin{aligned} (\langle f(v)w, z \rangle &= \langle f(w)v, z \rangle = -\langle v, f(w)z \rangle \\ &= -\langle v, f(z)w \rangle = \langle f(z)v, w \rangle \\ &= \langle f(v)z, w \rangle = -\langle f(v)w, z \rangle \rightarrow F=0) \end{aligned}$$

Thus, if M is connected, a Killing v.f. is entirely determined by its value at a point and the value of its first derivative.

PROPOSITION Consider the space of parallel sections of E w.r.t. D . Then Lie bracket inherited from Lie bracket of Killing v.f. is

$$[(z, A), (\eta, B)] = (A\eta - Bz, [A, B] + R(z, \eta))$$

Pf. By definition

$$[(z, A), (\eta, B)] = (\underbrace{[z, \eta]}, -\nabla[z, \eta])$$

$$\nabla_z \eta - \nabla_\eta z = A\eta - Bz$$

Now

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$$\begin{aligned} -\nabla_X [\zeta, \eta] &= -\nabla_X (A\eta - B\zeta) \\ &= -(\nabla_X A)\eta - A(\nabla_X \eta) \\ &\quad + (\nabla_X B)\zeta + B(\nabla_X \zeta) \\ &= -R(X, \zeta)\eta + AB(X) \\ &\quad \downarrow \text{Killing identity} \\ &\quad + R(X, \eta)\zeta - BA(X) \\ &= [A, B](X) + R(\zeta, \eta)X \end{aligned}$$

(M, g) Riem. manifold

$$G = \left\{ \varphi: M \rightarrow M \mid \begin{array}{l} \varphi^* g = g \\ \text{diffeom.} \end{array} \right\} \quad \text{Lie group of isometries}$$

$$\mathfrak{g} = \left\{ \zeta \in \mathfrak{X}(M) \mid \mathcal{L}_\zeta g = 0 \right\} \quad \begin{array}{l} \text{Killing algebra} \\ \text{(Lie algebra of infim. isometries)} \end{array}$$

QUESTION: What kind of Lie algebra is \mathfrak{g} ?

THE FLAT MODEL:

$$M = \mathbb{R}^m$$

$g =$ Euclidean flat metric

$$G = O(m) \ltimes \mathbb{R}^m$$

↑
isometries
fixing the
origin

↑
Translations

$$\mathfrak{g} = \mathfrak{euc}(m) = \mathfrak{so}(m) \ltimes \mathbb{R}^m \quad \text{Euclidean Lie algebra}$$

$$[A, B] = AB - BA$$

$$[A, v] = Av$$

$$[v, w] = 0$$

$$v, w \in \mathbb{R}^m$$

$$A, B \in \mathfrak{so}(m)$$

$$\mathfrak{euc}(m) = \mathfrak{so}(m) \ltimes \mathbb{R}^m$$

0 -1

is graded Lie algebra

THE ROUND SPHERE

$$M = S^m = \left\{ x \in \mathbb{R}^{m+1} \mid \|x\| = 1 \right\}$$

$$G = O(m+1) \quad \text{and} \quad \mathfrak{g} = \mathfrak{so}(m+1)$$

Fix $x \in S^m$ and write $V = T_x S^m$. The stabilizer at x

$H \cong O(V)$ with Lie algebra $\mathfrak{h} \cong \mathfrak{so}(V)$

$$\mathfrak{g} \cong \mathfrak{so}(V) \oplus V$$

v.s.

$$[A, B] = AB - BA$$

$$[A, v] = Av$$

$$[v, w] = \rho(v, w)$$

where $\rho = R|_x : \wedge^2 V \rightarrow \mathfrak{so}(V)$ is curvatures

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\mathfrak{g} is not graded but it is filtered.

Def. A filtration on a Lie algebra is nested sequence of subspaces

$$\mathfrak{g}^\bullet : \dots \supseteq \mathfrak{g}^{n-1} \supseteq \mathfrak{g}^n \supseteq \mathfrak{g}^{n+1} \supseteq \dots$$

↑
"degree at least n"

s.t.

$$\bigcap_n \mathfrak{g}^n = 0, \quad \bigcup_n \mathfrak{g}^n = \mathfrak{g}, \quad [\mathfrak{g}^n, \mathfrak{g}^m] \subseteq \mathfrak{g}^{n+m}$$

Def. Let \mathfrak{g}^\bullet be filtration of Lie algebra \mathfrak{g} . The associated graded Lie algebra \mathfrak{g}^\bullet is $\mathfrak{g}^\bullet = \bigoplus_{m \in \mathbb{Z}} \mathfrak{g}_m$, where $\mathfrak{g}_m = \mathfrak{g}^m / \mathfrak{g}^{m+1}$.

REM: $[\mathfrak{g}_m, \mathfrak{g}_m] \subseteq \mathfrak{g}_{n+m}$ is well-defined since $[\mathfrak{g}^{n+1}, \mathfrak{g}^m] + [\mathfrak{g}^n, \mathfrak{g}^{m+1}] \subseteq \mathfrak{g}^{n+m+1}$.

We may reverse point of view. Let

$$\mathfrak{g} = \bigoplus_{m \in \mathbb{Z}} \mathfrak{g}_m \quad [\mathfrak{g}_m, \mathfrak{g}_m] \subseteq \mathfrak{g}_{n+m}$$

be graded Lie algebra. Then a filtered deformation of \mathfrak{g} is a filtered Lie algebra \mathfrak{g}^\bullet s.t. $\mathfrak{g}_\bullet = \mathfrak{g}$.

Lie brackets of \mathfrak{g} are obtained by adding to those of $\mathfrak{so}(n)$ terms with positive degree.

EX: $\mathfrak{g} = \mathfrak{so}(n+1)$ is a filtered deformation of $\mathfrak{euc}(n)$

THM The Lie alg. \mathfrak{g} of isometries of (M, g) is filtered and its associated graded Lie algebra is subalgebra of $\mathfrak{euc}(n)$. " \mathfrak{g} is a filtered subdeformation of $\mathfrak{euc}(n)$ "

PF:

We localize Killing transport at point $x \in M$. Set

$$V = T_x M$$

$$E|_x = V \oplus \mathfrak{so}(V)$$

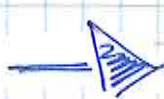
\mathfrak{g} is subspace of $E|_x$

$$0 \longrightarrow \mathfrak{h} \longleftarrow \mathfrak{g} \xrightarrow{ev_x} V' \longrightarrow 0$$

short exact sequence

$$V' = \{ z|_x \text{ with } z \in \mathfrak{g} \} \subseteq V$$

$$\mathfrak{h} = \{ z \in \mathfrak{g} \text{ with } z|_x = 0 \} \cong \{ (0, A) \in \mathfrak{g} \}$$



$$\mathfrak{g} \underset{\text{v.s.}}{\cong} \mathfrak{h} \oplus V'$$

Geometrically this amounts to choose splitting $V \longleftarrow V'$ $(v, X_v) \in \mathfrak{g}$
 for any $v \in V'$ a Killing v.f. z s.t. $z|_x = v$

Tracking back the Lie brackets of \mathfrak{g} on $\mathfrak{h} \oplus V'$ gives 5

$$[A, B] = AB - BA$$

$$[A, v] = Av + \underbrace{\delta(A, v)}_{\in \mathfrak{h}}$$

$$[v, w] = \underbrace{\alpha(v, w)}_{\in V'} + \underbrace{\rho(v, w)}_{\in \mathfrak{h}}$$

where

$$\alpha(v, w) = X_v w - X_w v$$

$$\delta(A, v) = [A, X_v] - X_{Av}$$

$$\rho(v, w) = [X_v, X_w] - X_{\alpha(v, w)} + R(v, w) \quad \blacksquare$$

$$\left([(\mathfrak{o}, A), (v, X_v)] = (Av, [A, X_v]) = (Av, X_{Av}) + (\mathfrak{o}, [A, X_v] - X_{Av}) \right)$$

Proposition page 2, bracket in $\mathfrak{f}_D(E)$ is Leibniz

$$[(\mathfrak{o}, A), (\mathfrak{o}, B)] = (\mathfrak{o}, [A, B])$$

$$[(v, X_v), (w, X_w)] = (X_v w - X_w v, [X_v, X_w] + R(v, w))$$

$$= (\alpha(v, w), X_{\alpha(v, w)})$$

$$+ (\mathfrak{o}, [X_v, X_w] - X_{\alpha(v, w)} + R(v, w))$$

