## Syllabus for MAT-3110 Differential Geometry I

- A. Elementary topics (warm-up and additional questions):
  - 1. Manifolds, submanifolds, orientation
  - 2. Tangent space and vector fields
  - 3. Cotangent space and 1-forms
  - 4. Exterior algebra: Differential forms
  - 5. De Rham differential *d*, relation to 3D vector calculus, and cohomology
  - 6. Lie Derivative and commutation relations between  $L_X$ , d,  $i_Y$ .
- B. Big topics (one to be chosen for the initial presentation):
  - 1. Pfaffian systems (vector distributions)
    - a. Integrable and non-integrable distributions [§ 4.1]
    - b. Frobenius theorem [§ 4.2]
    - c. Maurer-Cartan theory [§ 4.3]
  - 2. Surfaces in the Euclidean 3-space:
    - a. First, second fundamental form and Weingarten operator [§ 5.3]
    - b. Gaussian and mean curvature [§ 5.4]
    - c. Structure equations of surfaces and the Fundamental theorem [§ 5.2]
  - 3. Abstract Riemannian manifolds:
    - a. Riemannian metric [around]
    - b. Levi-Civita connection and equation of geodesics [lectures]
    - c. Curvature tensor and its components [§ 5.7]
  - 4. Lie groups and Homogeneous Spaces:
    - a. Lie groups and relations to Lie algebras [§ 6.1]
    - b. Examples of Lie algebras [lectures]
    - c. Transitive actions of Lie groups and homogeneous spaces [lectures and § 6.2]
  - 5. Symplectic geometry:
    - a. Symplectic vector spaces, isotropic and Lagrangian subspaces [§ 7.1]
    - b. Symplectic form, Darboux theorem, Contangent bundle [§ 7.2]
    - c. Poisson structure, Hamiltonian vector fields, integrals [§ 7.3]
- C. Practice (easy computations to be able to present on the blackboard):
  - Compute commutator of vector fields
  - Compute exterior product of differential forms
  - Hook vector field into a differential form
  - Lie derivate a form along a vector field
  - Compute de Rham differential of a differential form
  - Verify (Frobenius) integrability of a vector distribution
  - Compute Poisson bracket of two functions wrt the standard symplectic structure
  - Be able to find Lie algebra of a (classical matrix) Lie group